Practice Exercises

8.1 List three examples of deadlocks that are not related to a computer-system environment.

Answer:

- Two cars crossing a single-lane bridge from opposite directions.
- A person going down a ladder while another person is climbing up the ladder.
- Two trains traveling toward each other on the same track.

8.2 Suppose that a system is in an unsafe state. Show that it is possible for the threads to complete their execution without entering a deadlocked state.

Answer:
An unsafe state may not necessarily lead to deadlock, it just means that we cannot guarantee that deadlock will not occur. Thus, it is possible that a system in an unsafe state may still allow all processes to complete without deadlock occurring. Consider the situation where a system has twelve resources allocated among processes $P_0$, $P_1$, and $P_2$. The resources are allocated according to the following policy:

<table>
<thead>
<tr>
<th></th>
<th>Max</th>
<th>Current</th>
<th>Need</th>
</tr>
</thead>
<tbody>
<tr>
<td>$P_0$</td>
<td>10</td>
<td>5</td>
<td>5</td>
</tr>
<tr>
<td>$P_1$</td>
<td>4</td>
<td>2</td>
<td>2</td>
</tr>
<tr>
<td>$P_2$</td>
<td>9</td>
<td>3</td>
<td>6</td>
</tr>
</tbody>
</table>

Currently, there are two resources available. This system is in an unsafe state. Process $P_1$ could complete, thereby freeing a total of four resources, but we cannot guarantee that processes $P_0$ and $P_2$ can complete. However, it is possible that a process may release resources before requesting any further resources. For example, process $P_2$ could release a resource, thereby increasing the total number of resources to five. This allows pro-
cess $P_0$ to complete, which would free a total of nine resources, thereby allowing process $P_3$ to complete as well.

8.3 Consider the following snapshot of a system:

<table>
<thead>
<tr>
<th>Allocation</th>
<th>Max</th>
<th>Available</th>
</tr>
</thead>
<tbody>
<tr>
<td>$A B C D$</td>
<td>$A B C D$</td>
<td>$A B C D$</td>
</tr>
<tr>
<td>$T_0$</td>
<td>0 0 1 2</td>
<td>0 0 1 2</td>
</tr>
<tr>
<td>$T_1$</td>
<td>1 0 0 0</td>
<td>1 7 5 0</td>
</tr>
<tr>
<td>$T_2$</td>
<td>1 3 5 4</td>
<td>2 3 5 6</td>
</tr>
<tr>
<td>$T_3$</td>
<td>0 6 3 2</td>
<td>0 6 5 2</td>
</tr>
<tr>
<td>$T_4$</td>
<td>0 0 1 4</td>
<td>0 6 5 6</td>
</tr>
</tbody>
</table>

Answer the following questions using the banker’s algorithm:

a. What is the content of the matrix $Need$?

b. Is the system in a safe state?

c. If a request from thread $T_1$ arrives for (0,4,2,0), can the request be granted immediately?

Answer:

a. The values of $Need$ for processes $P_0$ through $P_4$, respectively, are (0, 0, 0, 0), (0, 7, 5, 0), (1, 0, 0, 2), (0, 0, 2, 0), and (0, 6, 4, 2).

b. The system is in a safe state. With $Available$ equal to (1, 5, 2, 0), either process $P_0$ or $P_3$ could run. Once process $P_3$ runs, it releases its resources, which allows all other existing processes to run.

c. The request can be granted immediately. The value of $Available$ is then (1, 1, 0, 0). One ordering of processes that can finish is $P_0$, $P_2$, $P_3$, $P_1$, and $P_4$.

8.4 A possible method for preventing deadlocks is to have a single, higher-order resource that must be requested before any other resource. For example, if multiple threads attempt to access the synchronization objects $A \cdots E$, deadlock is possible. (Such synchronization objects may include mutexes, semaphores, condition variables, and the like.) We can prevent deadlock by adding a sixth object $F$. Whenever a thread wants to acquire the synchronization lock for any object $A \cdots E$, it must first acquire the lock for object $F$. This solution is known as containment: the locks for objects $A \cdots E$ are contained within the lock for object $F$.

Compare this scheme with the circular-wait scheme of Section 8.5.4.

Answer:

This is probably not a good solution because it yields too large a scope. It is better to define a locking policy with as narrow a scope as possible. The circular wait approach is a reasonable approach to avoiding deadlock, and does not increase the scope of holding a lock.

8.5 Prove that the safety algorithm presented in Section 8.6.3 requires an order of $m \times n^6$ operations.
Practice Exercises

Answer:

The figure below provides Java code that implements the safety algorithm of the banker’s algorithm (the complete implementation of the banker’s algorithm is available with the source-code download for this text).

```java
for (int i = 0; i < n; i++) {
    // first find a thread that can finish
    for (int j = 0; j < n; j++) {
        if (!finish[j]) {
            boolean temp = true;
            for (int k = 0; k < m; k++) {
                if (need[j][k] > work[k])
                    temp = false;
            }
            if (temp) { // if this thread can finish
                finish[j] = true;
                for (int x = 0; x < m; x++)
                    work[x] += work[j][x];
            }
        }
    }
}
```

As can be seen, the nested outer loops—both of which loop through $n$ times—provide the $n^2$ performance. Within these outer loops are two sequential inner loops that loop $m$ times. The Big O of this algorithm is therefore $O(m \times n^2)$.

8.6 Consider a computer system that runs 5,000 jobs per month and has no deadlock-prevention or deadlock-avoidance scheme. Deadlocks occur about twice per month, and the operator must terminate and rerun about ten jobs per deadlock. Each job is worth about two dollars (in CPU time), and the jobs terminated tend to be about half done when they are aborted.

A systems programmer has estimated that a deadlock-avoidance algorithm (like the banker’s algorithm) could be installed in the system with an increase of about 10 percent in the average execution time per job. Since the machine currently has 30 percent idle time, all 5,000 jobs per month could still be run, although turnaround time would increase by about 20 percent on average.

a. What are the arguments for installing the deadlock-avoidance algorithm?

b. What are the arguments against installing the deadlock-avoidance algorithm?

Answer:
An argument for installing deadlock avoidance in the system is that we could ensure that deadlock would never occur. In addition, despite the increase in turnaround time, all 5,000 jobs could still run.

An argument against installing deadlock-avoidance software is that deadlocks occur infrequently, and they cost little when they do occur.

8.7 Can a system detect that some of its threads are starving? If you answer “yes,” explain how it can. If you answer “no,” explain how the system can deal with the starvation problem.

**Answer:**

Starvation is a difficult topic to define, as it may mean different things for different systems. For the purposes of this question, we will define starvation as the situation in which a process must wait beyond a reasonable period of time—perhaps indefinitely—before receiving a requested resource. One way of detecting starvation would be to first identify a period of time—\( T \)—that is considered unreasonable. When a process requests a resource, a timer is started. If the elapsed time exceeds \( T \), then the process is considered to be starved.

One strategy for dealing with starvation would be to adopt a policy whereby resources are assigned only to the process that has been waiting the longest. For example, if process \( P_a \) has been waiting longer for resource \( X \) than process \( P_b \), the request from process \( P_b \) would be deferred until process \( P_a \)'s request has been satisfied.

Another strategy would be less strict. In this scenario, a resource might be granted to a process that had waited less than another process, providing that the other process was not starving. However, if another process was considered to be starving, its request would be satisfied first.

8.8 Consider the following resource-allocation policy. Requests for and releases of resources are allowed at any time. If a request for resources cannot be satisfied because the resources are not available, then we check any threads that are blocked waiting for resources. If a blocked thread has the desired resources, then these resources are taken away from it and are given to the requesting thread. The vector of resources for which the blocked thread is waiting is increased to include the resources that were taken away.

For example, a system has three resource types, and the vector **Available** is initialized to \((4,2,2)\). If thread \( T_0 \) asks for \((2,2,1)\), it gets them. If \( T_1 \) asks for \((1,0,1)\), it gets them. Then, if \( T_0 \) asks for \((0,0,1)\), it is blocked (resource not available). If \( T_2 \) now asks for \((2,0,0)\), it gets the available one \((1,0,0)\), as well as one that was allocated to \( T_0 \) (since \( T_0 \) is blocked). \( T_0 \)'s **Allocation** vector goes down to \((1,2,1)\), and its **Need** vector goes up to \((1,0,1)\).

a. Can deadlock occur? If you answer “yes,” give an example. If you answer “no,” specify which necessary condition cannot occur.

b. Can indefinite blocking occur? Explain your answer.

**Answer:**
a. Deadlock cannot occur, because preemption exists.

b. Yes. A process may never acquire all the resources it needs if they are continuously preempted by a series of requests such as those of process C.

8.9 Consider the following snapshot of a system:

<table>
<thead>
<tr>
<th></th>
<th>A</th>
<th>B</th>
<th>C</th>
<th>D</th>
</tr>
</thead>
<tbody>
<tr>
<td>T₀</td>
<td>3</td>
<td>0</td>
<td>1</td>
<td>4</td>
</tr>
<tr>
<td>T₁</td>
<td>2</td>
<td>2</td>
<td>1</td>
<td>0</td>
</tr>
<tr>
<td>T₂</td>
<td>3</td>
<td>1</td>
<td>2</td>
<td>1</td>
</tr>
<tr>
<td>T₃</td>
<td>0</td>
<td>5</td>
<td>1</td>
<td>0</td>
</tr>
<tr>
<td>T₄</td>
<td>4</td>
<td>2</td>
<td>1</td>
<td>2</td>
</tr>
</tbody>
</table>

Using the banker’s algorithm, determine whether or not each of the following states is unsafe. If the state is safe, illustrate the order in which the threads may complete. Otherwise, illustrate why the state is unsafe.

a. Available = (0, 3, 0, 1)

b. Available = (1, 0, 0, 2)

Answer:

a. Not safe. Processes P₂, P₁, and P₃ are able to finish, but no remaining processes can finish.

  Safe. Processes P₁, P₂, and P₃ are able to finish. Following this, processes P₀ and P₄ are also able to finish.

8.10 Suppose that you have coded the deadlock-avoidance safety algorithm that determines if a system is in a safe state or not, and now have been asked to implement the deadlock-detection algorithm. Can you do so by simply using the safety algorithm code and redefining \( Max_i = Waiting_i + Allocation_i \), where \( Waiting_i \) is a vector specifying the resources for which thread \( i \) is waiting and \( Allocation_i \) is as defined in Section 8.6? Explain your answer.

Answer:

Yes. The \( Max \) vector represents the maximum request a process may make. When calculating the safety algorithm, we use the \( Need \) matrix, which represents \( Max - Allocation \). Another way to think of this is \( Max = Need + Allocation \). According to the question, the \( Waiting \) matrix fulfills a role similar to the \( Need \) matrix; therefore, \( Max = Waiting + Allocation \).

8.11 Is it possible to have a deadlock involving only one single-threaded process? Explain your answer.

Answer:

No. This follows directly from the hold-and-wait condition.