COMPATIBILITY AND COMMUTATIVITY IN NON-TWO-PHASE
LOCKING PROTOCOLS*

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ABSTRACT
Research on concurrency control mechanisms for database systems has had as a primary goal the discovery of techniques for allowing increased levels of concurrent execution of transactions. In this paper, we study this problem in the context of non-two-phase locking protocols which are defined for data bases in which a directed acyclic graph structure is superimposed on the data items. We introduce a new lock mode, called INV, with properties fundamentally different from locking modes previously studied and show how this allows increased concurrency. Through the introduction of the INV mode of locking we have enunciated a new principle of the theory of data base concurrency control. This principle involves the separation of the effects of the commutativity and compatibility of data manipulation operations. We then examine how the introduction of such a lock mode affects the occurrence of deadlocks in a system. Certain conditions under which deadlock-freedom is maintained are identified, and simple methods for removing deadlocks in other situations are presented.

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1. INTRODUCTION
Data base systems usually allow concurrent operations (read and write) by different transactions in order to improve performance. Safeguarding the consistency of the stored/retrieved data is of great significance under such circumstances. The most widely accepted approach to dealing with this problem is to define a transaction as a unit that preserves consistency (i.e., it is assumed that each transaction, when executed alone, transforms a consistent state of the data base into a new consistent state), and require that the outcome of processing a set of transactions concurrently be the same as one produced by running these transactions serially in some order. A system that ensures this property is said to be serializable [1]. Another important issue in data base management that sometimes arises as a result of actions taken by the concurrency control to maintain serializability is the problem of deadlocks. A system which does not allow deadlocks to occur is said to assure deadlock-freedom.

Serializability can be ensured via a number of concurrency control mechanisms, the most common one being a locking protocol. Such a protocol can be simply viewed as a restriction on when a transaction may lock and unlock each of the data base items. Locking a data item in a certain mode inhibits certain kinds of concurrent activity on that item until the item is unlocked. The first useful locking protocol developed was the two-phase locking (ZPL) protocol [1], which is characterized by the fact that a transaction is not allowed to lock a data base item after it has unlocked any other item. One drawback of the two-phase protocol is that it severely restricts the amount of concurrency allowed in a system.

This deficiency has led to the development of a number of non-two-phase locking protocols [5,6,11,12,14]. One of the non-ZPL protocols is the majority protocol (MP) presented in [5]. This protocol assures serializability and deadlock-freedom.

We introduce a new lock mode, called INV, in an extended version of MP and show how this leads to increased concurrency. Through the introduction of the INV mode of locking, which does not grant any access privileges (read/write) to the holder of the lock on the associated data item, we have enunciated a new principle of the theory of data...
base concurrency control. This principle involves the separation of the effects of commutativity (which relates to serializability) and compatibility (which relates to deadlock-freedom) of data manipulation operations. Thus we depart from the traditional approach to concurrency control which do not make this separation. We also see how the introduction of such a locking mode affects the problem of maintaining deadlock-freedom in a system and show how this problem can be handled.

This paper is organized as follows. In section 2, we introduce the invisible (INV) mode. In section 3, we discuss some existing problems and motivate the need for the INV mode. Then, in section 4, we present the Super Majority Protocol (SMP), which allows transactions to lock data items in INV, S and X modes. SMP is shown to assure serializability. Section 5 treats the issue of deadlocks in SMP, which is shown to be deadlock-free for rooted trees but not for more general DAG's. Simple and effective methods for handling deadlocks when they occur are given.

2. LOCK MODES AND THEIR PROPERTIES

Let a data base consist of a set of data items V. We ignore the exact nature of the granularity of the items, but it should be noted that we do not consider in our work protocols supporting a variable granularity of locking [4, 8]. Associated with the data base is a set of consistency constraints, the exact nature of which is not of concern to us. A state of the data base containing an assignment of values to the elements of V. A given data base state is said to be consistent if that state satisfies the consistency constraints.

One of the components of the data base system is a lock manager which receives and processes the lock requests of the transactions. This means that once a transaction issues a lock request, it cannot proceed until that lock has been granted. In all the protocols to be presented here, locks can only be obtained one at a time. Further, once a data item is unlocked by a transaction it cannot be relocked by that transaction.

We assume that the transactions are well-formed; that is, every action that a transaction performs is permitted by the locks that it holds at the time the action is performed and all locks held by a transaction are released by the transaction before it terminates. We also assume that every transaction when run alone on a consistent state of the data base transforms the latter into a consistent state.

The protocols that we present in this paper allow three modes of locking: X (exclusive), S (shared) and INV (invisible). These modes can be obtained via the LX, LS and LINV instructions, respectively. Locks can be released using the UN instruction. If a transaction holds an X mode lock on a data item, it can read and modify that data item, and if it holds an S mode lock, it can only read the data item. When holding an INV mode lock, the transaction can neither read nor modify the data item (i.e., the data item is invisible to the transaction). While the INV mode is a kind of intention mode in the sense that it conveys some information about what kind of locks a transaction may acquire in the future, it bears no further resemblance to the intention modes of [4, 8], which are used to support variable granularity of locking. The motivation for the introduction of the INV mode will become apparent to the reader when we present an example in Section 3.

Given a set of locking modes, we can define the compatibility relation among them as follows. Suppose that a transaction T₂ requests a lock of mode A on item e on which transaction T₁ currently holds a lock of mode B. If the lock manager is allowed to grant T₂'s request, then the presence of the mode B lock, then we say mode A is compatible with mode B. Such a relation, particularly on a relatively few locking modes, can conveniently be represented by a matrix. The compatibility relation among the 3 modes of locking used in this paper is given by the matrix, COMP (Figure 2-1). An element, say COMP(I,J), of the matrix has the value T if and only if mode J is compatible with mode I.

X | S | INV
---|---|---
X | T | |
S | T | |
INV | T | T

Figure 2-1: Lock Compatibility Matrix COMP

Note that INV mode is compatible with X mode, but not with S mode. At any time one X mode lock and zero or more INV mode locks can be simultaneously held (by different transactions) on a particular data item. A subsequent X mode lock request has to wait until the currently held X mode lock is released.

Another important characteristic of a set of locking modes is the commutativity relation among them. We say locking modes A and B are commutative if all operations which a transaction is allowed to perform while holding a mode A lock on an item and all operations which are allowed under a mode B lock are commutative. Thus, the results produced on an item by two transactions, one holding a mode A lock and the other a mode B lock, will be identical regardless of the order in which the transactions acquire locks on the item. As with the compatibility relation, the commutativity relation is conveniently represented by a matrix. The commutativity matrix COMM for the locking modes used here is given in Figure 2-2. COMM(I,J) = T iff modes I and J are commutative. For example, mode S is not commutative with mode X. If one operation reads data item v and a subsequent operation modifies v, then changing the order of these two operations must be assumed to result in a different value being read by the read operation. On the other hand, mode S is compatible with mode S since changing the order of reads will not change the value read. Notice that even though the S and
INV modes are incompatible, they are still commutative.

<table>
<thead>
<tr>
<th>X</th>
<th>S</th>
<th>INV</th>
</tr>
</thead>
<tbody>
<tr>
<td>T</td>
<td>T</td>
<td>T</td>
</tr>
</tbody>
</table>

Figure 2-2: Lock Commutativity Matrix COMM

In previous research on locking, the COMP and COMM matrices were assumed to be identical, as are the matrices presented in this section if we ignore the rows and columns corresponding to the INV mode. Because existing techniques for proving the serializability and deadlock-freedom of locking protocols depend on this fact, we have been forced to augment them with some new methodologies.

We now introduce some standard definitions which will be required in the subsequent technical discussion.

Definition 2-1: A history H is the trace, in chronological order, of the concurrent execution of a set of transactions \( T = \{T_0, ..., T_{n-1}\} \).

Definition 2-2: We define the \( <e \) and \( < \) relations (the "precedes" relations) on a history H of a set \( T \) of transactions as follows:

\( T_1 <e T_j \iff T_1 \text{ has held an } M_i \text{ mode lock on } e \text{ initially and } T_j \text{ has held an } M_j \text{ mode lock on } e \text{ later, and } \text{COMP}(M_i, M_j) \neq T \).

\( T_i < T_j \iff \exists e [T_i <e T_j] \)

We note that the \( < \) relation (the "precedes" relation) pertains to the serializability of the history H. In the above case, it means that in an equivalent serial schedule \( T_i \) must appear before \( T_j \). Note the close relationship between the commutativity relation on lock modes and the precedence relation on histories.

Claim 2-1: A protocol assures serializability if and only if for all concurrent executions of transactions following it the associated relation \( < \) is acyclic.

Definition 2-3: We define the \( \rightarrow e \) and \( \rightarrow \) relations (the "wait-for" relations) as follows:

\( T_1 \rightarrow e T_j \iff T_i \text{ is currently holding a lock on } e \text{ in } M_i \text{ which is incompatible with the mode } M_i \text{ in which } T_j \text{ has requested a lock on } e \text{ (that is, COMP}(M_i, M_j) \neq T) \).

\( T_i \rightarrow T_j \iff \exists e [T_i \rightarrow e T_j] \)

Note that the relationship between the compatibility relation among locking modes and the waits-for relation on histories is similar to that noted above for commutativity and precedence.

Claim 2-2: A protocol assures deadlock-freedom if and only if for all concurrent executions of transactions following it the associated relation \( \rightarrow \) is acyclic.

3. EXISTING PROTOCOLS

The majority protocol (MP) for databases in which the data items are organized as directed acyclic graphs (DAGs) was presented in [5]. It allows transactions to obtain only X mode locks. For simplicity of presentation we restrict our attention here to the version of MP for rooted DAGs.

Let \( V \) be the set of vertices of a rooted DAG with the vertex \( R \) being the root and each vertex a data item.

1. Any vertex may be locked first.

2. Subsequently, a vertex \( v \) can be locked only if locks are held on at least a majority of the parents of \( v \).

3. Vertices may be unlocked any time.

Theorem 3-1: The majority protocol assures serializability and deadlock-freedom.

Proof: See [5].
4. THE SUPER MAJORITY PROTOCOL

Let us illustrate how some potential concurrency is lost due to the requirements of MP'. Consider the system consisting of two entities R and Q, where Q is the son of the root R. Suppose that, at a certain point in time, transaction T₁, which needs to update only R, obtains an X mode lock on item R. Immediately after that, transaction T₂ starts, and it needs to update only Q. T₂ is required to acquire an X mode lock on R before it can lock Q. As a consequence of this requirement, T₂ is forced to wait until T₁ finishes its updating of R. Thus some potential concurrency is lost.

What we would like to see happen is T₂ being allowed to "overtake" (or "step-over") T₁ and lock Q. In this way, both T₁ and T₂ will be able to perform their updates in parallel. It is only to provide this "overtaking" ability to update transactions, which could potentially lead to an increased level of concurrency, that we have introduced the IN (invisible) mode of locking. We now present a protocol which incorporates this capability into MP'. This protocol, which we call the Super Majority Protocol (SMP), is also intended for data bases organized as rooted DAGs.

We classify the transactions that access the data base into two types:

1. Update transactions -- Those transactions that can issue INV, X and S mode lock requests (at least one X mode lock request must be issued).
2. Read-only transactions -- Those transactions that can issue only S mode lock requests.

The rules of the SMP protocol are:

1. Read-only transactions may start anywhere. They should obey the majority protocol rules stated in the last section.

2. Update transactions:
   1. Each transaction must start at the root; it may lock the root in either INV or X mode.
   2. Subsequently, a vertex v can be locked in mode
      INV -- only if INV mode locks are being held on at least a majority of the parents of v, and the first X mode lock has not been acquired so far.
      X -- only if X mode locks are being held on at least a majority of the parents of v, or, if this is the first X mode lock request, all the vertices so far locked (in INV mode) are predecessors of v and INV mode locks are being held on at least a majority of the parents of v.
   3. Vertices may be unlocked any time.

Observations:

- All the vertices locked in INV mode, if any, will span a rooted DAG, with R as the root.
- All the vertices locked in X mode will span a rooted DAG, with the first vertex to be locked in X mode as the root.
- Once the first X mode lock request has been issued, no more INV mode lock requests can be issued.
- In contrast to the vertices locked in INV and X modes, all the vertices, if any, locked by an update transaction in S mode need not necessarily span only a single connected component.
- Any vertex locked in INV mode must be an ancestor of any other vertex locked in S or X mode. Thus no "useless" INV mode locking is allowed. The INV mode locks are "helpful" only to get the first X mode lock.
- All vertices locked in S mode by an update transaction must be successors of at least the first vertex to be locked in X mode.

We claim that SMP supports more concurrency than MP' for the following reasons. Any transaction which was designed to follow MP' (on a particular rooted DAG) can be run under SMP without any change (on the same DAG). In addition to those transactions, SMP permits other transactions also (update transactions with INV and/or S mode locks). Compared to MP', SMP permits an update transaction to "overtake" other update transactions. Unlike the former, it does not force the update transactions to be serialized according to the order in which they acquired a lock on the root. Moreover, even without the inclusion of invisible locks there may exist certain transactions which request both exclusive and shared locks which are allowed to run under SMP but not under MP'.

Note that in [7] it was shown that MP' is an example of a general methodology for extending serializable protocols allowing only X locks to serializable protocols with both X and S locks. The strategy of increasing concurrency in such protocols using new locking modes with non-equivalent compatibility and commutativity relations is thus a general strategy applying to a wide class of protocols rather than a single
Theorem 4-1: The Super Majority Protocol assures serializability.

Proof: Before proceeding with the proof, we need to state some basic definitions and lemmas, the proofs of which are omitted for the sake of brevity.

Definition 4-1: Let $\theta$ denote a vertex–enumeration function $\theta: V \rightarrow \{0, 1, \ldots\}$, where $V$ is the set of vertices of the rooted DAG, such that if vertex $v$ is a descendant of vertex $f$, then $\theta(f) < \theta(v)$.

Definition 4-2: Let $L(T_i)$ be the set of all vertices locked by $T_i$, $LINV(T_i)$ be the set of vertices locked in INV mode by $T_i$, $LX(T_i)$ be the set of vertices locked in X mode by $T_i$ and $LS(T_i)$ be the set of vertices locked in S mode by $T_i$. A lock is held on each member of these sets by $T_i$ during its execution.

When $L(T_i) \cap L(T_j) \neq \emptyset$, let the lowest common ancestor of $T_i$ and $T_j$, denoted $LCA(T_i, T_j)$, be the vertex $e$ such that $\theta(e) = \min\{\theta(a) \mid a \in L(T_i) \cap L(T_j)\}$.

Definition 4-3: When $T$ is an update transaction, let $FX(T)$ be the first vertex to be locked in X mode by transaction $T$ (If this vertex is $e$ then $\theta(e) = \min\{\theta(v) \mid v \in LX(T) \cup LS(T)\}$). When $T$ is a read-only transaction, let $FS(T)$ be the first vertex to be locked in S mode (If this vertex is $f$ then $\theta(f) = \min\{\theta(v) \mid v \in LS(T)\}$). Let $FV(T)$ be the first vertex to be locked by transaction $T$ in a non-INV mode. $FV(T) = FX(T)$, if $T$ is an update transaction. Otherwise, $FV(T) = FS(T)$.

Lemma 4-1: If $u$ and $w$ are distinct vertices in $L(T_1) \cap L(T_2)$, then there exists a (undirected) chain in the underlying graph between $u$ and $w$ which lies entirely in $L(T_1) \cap L(T_2)$.

Lemma 4-2: If $LX(T_1) \cap LS(T_2) \neq \emptyset$ and $T_2$ is a read-only transaction then $FS(T_2) \in LX(T_1) \cup LINV(T_1)$.

Lemma 4-3: If $LX(T_1) \cap LS(T_2) \neq \emptyset$ and $T_2$ is an update transaction then $FX(T_2) \in LX(T_1) \cup LINV(T_1)$ and $FX(T_1) \in L(T_2)$.

Lemma 4-4: If $LX(T_1) \cap LX(T_2) \neq \emptyset$ then $FX(T_2) \in LX(T_1) \cup LINV(T_1)$ and $FX(T_1) \in LX(T_2)$ and either $FX(T_2) \in LX(T_1)$ or $FX(T_1) \in LX(T_2)$.

Lemma 4-5: When $T_1$ and $T_2$ are update transactions, if $LS(T_1) \cap LS(T_2) \neq \emptyset$, then either $FX(T_1) \in LX(T_2)$ or $FX(T_2) \in LX(T_1)$ and $LS(T_1)$.

Lemma 4-6: (Composition lemma) If $T_1$ is an update transaction with $v \in LX(T_1)$ and no successor of $v \in L(T_1)$ and $T_2$ is a read-only transaction with $FX(T_2) = v$, then there exists a transaction $T_3$ following SMP such that $L(T_3) = L(T_1) \cup L(T_2)$, $LINV(T_3) = LINV(T_1)$, $LX(T_3) = LX(T_1) \cup LS(T_2)$ and $LS(T_3) = LS(T_1) \cup LS(T_2) - \{v\}$.

Proof of Theorem 4-1: Assume by contradiction that SMP does not assure serializability. Then without loss of generality there exists a history of a set of transactions which follow SMP for which the precedence relation ($<$) contains a minimal cycle of the form:

$$T_0 < T_1 < \cdots < T_{n-1} < T_0$$

Now remove the last lock instruction issued by $T_0$ along with its associated UN instruction from both $T_0$ and the history. Continue removing the last remaining lock-unlock pair until any further removals would break the cycle. The remaining pattern of locking instructions of $T_0$, which we call $T'_0$, still obeys SMP. Continue performing this truncation operation on each transaction in turn to obtain $T'_0$ through $T'_{n-1}$ and a new history containing the cycle:

$$T'_0 < u_0 < T'_1 < u_1 < \cdots < u_{n-2} < T'_{n-1} < u_{n-1} < T'_0$$

Remember that $T'_i < u_i < T'_{i+1}$ means that at least either $T'_{i+1} \cup u_i$ had locked $u_i$ in X mode. The $u_i$s in the cycle have been chosen in such a way that (when $n > 2$) for no ancestor $v$ of $u_i$, $T'_i < v < T'_{i+1}$.

Non-Distinct Vertices:
It is possible for $u_i$ and $u_{i-1}$ to be the same vertex $u$, giving us the following:

$$T'_{i-1} < u_i < T'_i < u_{i+1}$$

This can happen only when $T'_{i-1}$ and $T'_{i+1}$ had locked $u$ in S mode and $T'_i$ had locked $u$ in X mode. Note that no other vertex $v_i$ can be equal to $u$ since in that case either $T'_{i-1}$ or $T'_{i+1}$ must have locked $u = u_i$ in X mode, thus resulting in a shorter cycle with $T'_i < T'_{i-1}$ or $T'_{i+1} < T'_i$, contradicting the assumed minimality of the cycle.

Note that in the above case $T'_i$ must be an update transaction, while either $T'_{i-1}$ or $T'_{i+1}$ must be a read-only transaction. The failure condition follows from Lemma 4-5 and the assumed minimality of the cycle.

We proceed with the proof by induction on the length ($n$) of the minimal cycle.

in the sequel, for brevity we drop the superscript (') of the transactions and write $T_i$ for each transaction $T'_i$. Thus the minimal cycle becomes:

$$T_0 < u_0 < T_1 < u_1 < \cdots < u_{n-2} < T_{n-1} < u_{n-1} < T_0$$

Basis Step:
As the basis of the induction we make $n = 2$ and assume the existence of the cycle

$$T_0 < u_0 < T_1 < u_1 < T_2$$

Now consider the vertex $w$ such that $\theta(w) = \max\{\theta(FV(T_0)), \theta(FV(T_1))\}$. From Lemma 4-1 there must be a path, common to $T_0$ and $T_1$, from $u$ to $v$. From the rules of the protocol it should be clear that if a transaction had locked $u$ or $v$ in X mode then it must have locked $w$ also in X mode. By
"pushing" the conflict \( T_i \prec T_j \) along the common path to \( v \) we will get \( T_0 \prec T_j \). Similarly by "pushing" the conflict \( T_k \prec T_l \) we will get \( T_0 \prec T_l \). Thus we will get a contradiction and hence the impossibility of a cycle of length 2.

**Induction Step:**

Notice that each \( T_1 \) has to be either \( FV(T_1) \) or \( FV(T_1) \) and that for each \( T_1 \), \( FV(T_1) \) is \( u_i \) (only if \( u_i \) is a descendant of \( u_j \)).

Subcase 1: \( u = FV(T_j) \). This immediately implies that \( T_j \) is a read-only transaction. \( u \) may or may not be \( FV(T_1) \). Similarly \( u \) may or may not be \( FV(T_1) \). (Note that if \( u \) is not equal to \( FV(T_1) \) then \( u \) must be \( FV(T_1) \), as pointed out before).

From Lemma 4-6 we know that we can merge \( T_{i-1} \) and \( T_{i+1} \) and get, say, \( T_1 \) which follows the SMP. Now the above history, after the removal of one unlock of \( T_1 \) and one lock of \( T_1 \), and appropriate renaming of the other instructions of the two transactions, will look as follows:

\[
\begin{align*}
\text{T}_{i-1} &\text{ LS u;} \quad \text{T}_{i-1} \text{ UN u;} \quad \text{T}_i \text{ LX u;} \quad \text{T}_{i+1} \text{ UN u;} \\
\end{align*}
\]

This is still a legal history since during the interval II other transactions (if any) could have held \( u \) in only the INV mode and those transactions would still be able to hold those locks simultaneously with \( T_j \) since the INV and X modes are compatible.

By merging the two transactions we have obtained the relation

\[
T_{i-1} \prec u \prec T_{i+1} 
\]

and hence a cycle of length \( n-1 \).

Subcase 2: \( u \neq FV(T_j) \). We know immediately that \( u \) must be \( FV(T_1) \). Let \( v \) be the vertex such that \( \delta(v) = \max(\delta(FV(T_1))) \). Assuming that \( v \neq u_1 \), it can be shown that the history must be of the form:

\[
\begin{align*}
&\prec.16.-.\rightarrow T_{i-1} \text{ LS v;} \quad \text{T}_{i-1} \text{ UN v;} \prec.13.-.\rightarrow \\
&T_j \text{ LIN} v; \quad \prec.15.-.\rightarrow T_1 \text{ UN v;} \prec.14.-.\rightarrow \\
&T_{i+1} \text{ LS v;} \quad \cdots \quad T_{i+1} \text{ UN v;} \quad \cdots \\
\end{align*}
\]

Briefly, the reasons as to why this should be the case are: We know that \( T_{i-1} \) and \( T_{i+1} \) locked \( v \) in S mode and that \( T_j \) locked \( v \) in INV mode.

Without loss of generality assume that \( T_{i+1} \) is a read-only transaction and that \( T_j \) is an update transaction (i.e., \( v = FV(T_{i+1}) \)).

By inducting on the length of the path common to \( T_{i-1} \) and \( T_{i+1} \), from \( v \) to \( u \), it can be easily shown that \( T_j \) must have locked \( v \) before \( T_{i+1} \) locked it. Now we need to show that \( T_{i-1} \) must have locked \( v \) before \( T_j \) locked it. Consider the path \( v = w_0 \rightarrow w_1 \rightarrow \cdots \rightarrow w_{k-1} \rightarrow w_k = u \), common to \( T_{i-1} \) and \( T_j \), \( v \) must be the only parent of \( w_k \). Due to the fact that the \( T_j \) were defined so that the \( L(T_j) \) had the minimal number of elements, it must be that the lock on \( w_k \) \( (j=1, \ldots, k) \) must have been obtained because \( T_{i-1} \) had a lock on \( w_{k-1} \) (in addition to other locks).

From the rules of SMP, we can deduce that since \( T_{i-1} \) had locked \( v \) (i.e., \( w_0 \)) in S mode it could have locked \( w_k \) only in S mode. By repeating this argument we can show that all vertices on the common path must have been locked by \( T_{i-1} \) in S mode. Once this is known it can be easily shown that \( T_{i-1} \) must have locked \( v \) before \( T_j \) locked it.

Notice that during the time interval from the point of unlocking of \( v \) by \( T_{i-1} \) to the point of unlocking of \( v \) by \( T_{i+1} \), no transaction could have locked \( v \) in X mode. During intervals 13 and 14 some transactions could have locked \( u \) in S mode.

Within subcase 2 we need to consider two cases.

**Subcase 2a: \( v = FV(T_{i+1}) \).** This means that \( u \neq v \).

We modify the history by truncating \( T_j \) so that it acquires locks only on the ancestors of \( v \) in INV mode, and a lock on \( v \) in X mode (instead of INV mode) and subsequently no other locks (i.e., after the acquisition of the X mode lock on \( v \), \( T_j \) will consist of only unlock instructions). By doing this the history becomes:

\[
\begin{align*}
\text{T}_{i-1} &\text{ LS v;} \quad \text{T}_{i-1} \text{ UN v;} \quad \text{T}_1 \text{ LX v;} \quad \text{T}_{i+1} \text{ UN v;} \\
\text{T}_1 \text{ UN v;} \quad \cdots \quad \text{T}_{i+1} \text{ LS v;} \quad \cdots \quad \text{T}_{i+1} \text{ UN v;} \\
\end{align*}
\]

We still maintain \( T_{i-1} \prec T_1 \prec T_{i+1} \).

This history is legal since we know that no transaction could have acquired an X or S mode lock on \( v \) during the interval 13. This would have contradicted the
induction hypothesis. If there is no such transaction then we have an instance of subcase 1 and we can take the steps outlined there to show the impossibility of a minimal cycle of length n.

Subcase 2b: \( v \notin \text{FV}(T_{i+1}) \). This means that \( v \) must be \( \text{FV}(T_{i-1}) \) and hence \( T_{i-1} \) must be a read-only transaction. If \( u \neq v \), just as in subcase 2a modify \( T_i \) so that it acquires an X mode lock on \( v \). If after that the cycle becomes shorter then the proof is finished. Otherwise, whether \( u \) equals \( v \) or not, we need to do something more (unlike in the case of subcase 2a we do not now have an instance of subcase 1). Notice that this means that the vertex \( u_{i-2} \) must be a successor of \( v \) and that \( v \) had not been locked in X mode by any transaction and that \( v \) had been locked in S mode by only \( T_{i-1} \) and \( T_{i+1} \).

We merge transactions \( T_{i-1} \) and \( T_{i} \) to get the transaction \( T'_{i} \). \( T'_{i} \) is made to acquire an X mode lock on \( v \). We modify the history by shifting all the lock and unlock instructions of \( T_i \) except the unlock \( v \) instruction to the very beginning of the history, removing \( T_{i-1} \text{LS} \) \( v \) and replacing \( T_{i-1} \text{UN} \) \( v \) with \( T'_{i} \text{LX} \) \( v \).

These changes leave the new history in a legal state since during interval \( I_6 \) some other transactions (if any) could have locked \( v \) only in INV mode and by letting \( T'_{i} \) hold an X mode lock on \( v \) during that period we are not disallowing the former.

By merging the two transactions we have obtained the relation \( T_{i-2} \prec u_{i-2} \prec T'_{i} \prec T_{i+1} \) and a cycle of length \( n-1 \), thus contradicting the induction hypothesis.

Thus we have proved the serializability of the SMP.

5. DEADLOCKS IN SMP

One of the consequences of the use of a locking protocol to assure serializability is the possibility of creating deadlocks. In this section we will show that on a DAG which is a rooted tree, SMP assures deadlock-freedom, while on an unrestricted DAG, deadlocks are possible. To illustrate this point consider the system depicted in Figure 5.1. The following sequence of execution results in a deadlock:

\[
T_2 \text{LINV} R; T_2 \text{LINV} B; T_2 \text{LINV} C; T_2 \text{LINV} E; T_2 \text{UN} B; T_2 \text{UN} C; T_1 \text{LS} B; T_1 \text{LS} D; T_1 \text{LS} C; T_1 \text{UN} B; T_3 \text{LS} R; T_3 \text{LS} F; T_3 \text{LX} B; T_3 \text{LX} D; T_1 \text{LS} E; T_2 \text{LINV} F;
\]

Before we present the proof of the former result, we present a general result concerning deadlocks in any protocol (not restricted to SMP) supporting the INV, X and S modes of locking:

5.1 A General Result on Deadlocks

Definition 5-1: When we view a protocol as a set of allowed transaction patterns, a protocol \( P \) is said to be closed under truncation if for every locking pattern \( P \), the instructions referring to the last item locked by \( T \) can be deleted from \( T \) to form a new pattern \( T' \) of \( P \).

A locking protocol is called a T-protocol if it is closed under truncation. Most locking protocols that have been proposed in the literature are T-protocols.

One of the results of [14] is that if a set of transactions following a T-protocol \( P \) which assures serializability are involved in a deadlock of the form

\[
T_0 \rightarrow u_0 \rightarrow T_1 \rightarrow u_1 \rightarrow \cdots \rightarrow u_{n-2} \rightarrow T_{n-1} \rightarrow u_{n-1} \rightarrow T_0
\]

then for any pair of transactions \( T_i \) and \( T_j \) involved in the deadlock, \( T_i \neq T_j \) and \( T_i \neq T_j \).

While [14] considered only the X mode, the above result is true even when we consider T-protocols which allow the X and S modes [2]. The result is not true in general if we consider any T-protocol which supports the INV, X and S modes. As a counterexample, consider SMP and the deadlock situation presented in Figure 5.1, where we have the cycle:

\[
T_1 \rightarrow E \rightarrow T_2 \rightarrow G \rightarrow T_3 \rightarrow D \rightarrow T_1
\]

In this case the relation \( T_1 \prec B \prec T_3 \) is true at the time of the deadlock.

However, if we impose a few additional restrictions, then the above result will again hold even when INV mode locks are allowed.

Theorem 5-1: If a set of transactions following a T-protocol \( P \) which assures serializability and which supports the X, S and INV modes of locking get involved in a deadlock of the form...
Now we take the following steps:

Case 1: ui is held in INV mode by Ti+1. This means that Ti is being requested by Ti in S mode. It also means that Ti+1 may be requesting an INV, X or S mode lock on ui+1. Since Ti+1 cannot obtain redundant INV locks, it must be the case that ui is an ancestor of ui+1. Thus ui must be locked in INV mode by any transaction due to the minimality of the cycle, thus giving us a cycle in which m is less than k and contradicting the induction hypothesis.

By Theorem 5-1 this cannot be the case, so ui is an ancestor of ui+1. A contradiction of the induction hypothesis is obtained regardless.

Case 2: ui is held by Ti+1 in S mode. This means that Ti must be needing ui in INV mode. It also means that Ti+1 is being held by Ti in INV mode. Now if we consider the pair of vertices ui-1 and ui then we have an instance of Case 1. Hence we can take the steps outlined under Case 1 to handle this case also.

5.2 Deadlock-Freedom for Rooted Trees


Proof: The technique that we use for proving deadlock-freedom is the following. Assume the existence of a minimal deadlock cycle involving n transactions. We perform an induction on m, the number of ui's which are either held or requested in INV mode by transactions in the cycle at the time of deadlock, to show that such a cycle is impossible.

Base Step: m = 0.

In this case each Ti in the cycle accesses both ui-1 and later ui in non-INV modes. Moreover, Ti must access every vertex on the chain connecting ui-1 and ui in the tree. This is obviously true if ui-1 is an ancestor of ui. Otherwise ui-1 and ui have a common ancestor e in the chain. This ancestor cannot be locked in INV mode by any transaction obeying the protocol, and thus neither can any of its descendants on paths to ui-1 and ui. Suppose that ui-1 is not an ancestor of ui. Then Ti locks the father f of ui-1 in non-INV mode. As we have just seen, so does Ti-1, so that either Ti-1 = Ti or Ti-1 = Ti before the deadlock occurs. By Theorem 5-1 this cannot be the case, so ui-1 is indeed an ancestor of ui. Since this is true for all transactions in the cycle, the tree must contain a cycle connecting ui-1 through ui and we obtain a contradiction. Thus no deadlock involving only exclusive and shared locks can exist.

Induction Step: m = k.

From the minimality of the cycle we know that every vertex ui is being held by only one transaction (namely Ti+1) at the time of the deadlock and that all the ui's are distinct.

Let us consider the vertex ui such that

\[ T_i \rightarrow u_i \rightarrow T_{i+1} \rightarrow u_{i+1} \]

There are two cases.

Case 1: ui is held in INV mode by Ti+1. This means that Ti+1 is being requested by Ti in S mode. It also means that Ti+1 may be requesting an INV, X or S mode lock on ui+1. Since Ti+1 cannot obtain redundant INV locks, it must be the case that ui is an ancestor of PV(Ti+1) and thus of ui+1.

Now we take the following steps:

1. Find the last transaction (call it Ti), if any, in the history which locked the vertex ui in a non-INV mode. If Ti locked ui in X mode, remove the Ti UN wi instruction so that Ti continues to hold ui.

By doing this we get a history in which

\[ T_0 \rightarrow u_0 \rightarrow T_1 \rightarrow u_1 \rightarrow T_2 \rightarrow u_2 \rightarrow \cdots \rightarrow T_{n-1} \rightarrow u_{n-1} \rightarrow T_0 \]

At least transaction Ti+1 would have been eliminated from the cycle and ui+1 is no longer held in INV mode by any transaction other than Ti+1, which requests locks for the vertices on the path in the tree from ui to ui+1 to that point in the history where all transactions other than Ti+1 are waiting for their requests to be granted.

Replace all instructions requesting INV mode locks with those requesting X mode locks. It may be the case that Ti+1 gets "stuck" even before it could request a lock on ui+1. This will happen if a vertex, say v, which is predecessor of ui+1 is currently being held in X or S mode by a transaction, say Tj, in the deadlock cycle and Ti+1 requests an X mode lock on v. Thus we have a contradiction of the induction hypothesis.

This may result in the cycle length becoming smaller than n (we say "may" because it is possible that Ti and Ti+2 are the same transaction). In the worst case Ti+1 will get "stuck" requesting a lock on ui+1. In any case, we will have reduced the number of ui's on which an INV mode lock is needed or being held by at least 1. There will be a reduction of 2 if Ti+1 had requested an INV mode lock on ui+1. A contradiction of the induction hypothesis is obtained regardless.

Case 2: ui is being held by Ti+1 in S mode. This means that Ti must be needing ui in INV mode. It also means that ui-1 is being held by Ti in INV mode. Now if we consider the pair of vertices ui-1 and ui then we have an instance of Case 1. Hence we can take the steps outlined under Case 1 to handle this case also.

5.3 Handling Deadlocks in DAGs

The simplest way to avoid the possibility of deadlocks is to force the transactions to lock vertices in an order (see Definition 4-1) consistent with their enumeration. Forcing the transactions to follow this rule could potentially lead to reduced concurrency since some vertices may remain locked for a time span longer than the time span during which they otherwise would remain locked.

In general, when deadlocks are allowed to occur, they can be resolved using a number of recovery schemes [3, 10, 13], which usually require one or more transactions to be rolled back (i.e., the effects of the transactions to be "undone").
a transaction has been chosen for being rolled back it could be rolled back completely (all the actions of the transaction are "undone") or partially (the transaction is rolled back only to the point in its execution where it is about to acquire a lock on that item which is held by this transaction at the time of the deadlock and which is being needed by the neighboring transaction in the deadlock cycle - by doing this the neighboring transaction can be granted that lock and the deadlock cycle broken). Rolling back one transaction may force some other transactions which subsequently read value of data items produced by the former also to be rolled back. This phenomenon is called cascading rollback.

Once we know that deadlocks can occur and that they must be dealt with, it is important to see if cascading rollbacks can be avoided. The advantages of avoiding cascading rollbacks are:

1. Only one transaction needs to be rolled back to resolve any deadlock. This leads to a decrease in the amount of partial transaction executions that are repeated.

2. More importantly, transaction executions need not be monitored to keep track of transaction dependencies (information about which transaction read which transaction's output). This is in systems where cascading rollbacks are inevitable, such information is necessary to determine, when a decision is made to rollback a particular transaction, what other transactions must also be rolled back.

3. If cascading rollbacks are not avoided, then an increase in the delay between the time at which a deadlock occurs and the time at which it is detected could potentially lead to an increase in the number of transactions that need to be rolled back.

It turns out that with a very simple condition (which does not restrict the transactions' ability to lock anything that the unrestricted version of the protocol allows) such rollbacks can be avoided. Even the rollback that needs to be done for a single transaction turns out to be a very simple one. It does not require the restoration of any item's value. Before we discuss that simple condition we need to state a property that holds for any possible deadlock cycle under SMP.

Theorem 5-3: If the concurrent execution of a set of transactions following SMP results in a deadlock cycle of the form

$t_0 \rightarrow t_1 \rightarrow \ldots \rightarrow t_k \rightarrow \ldots \rightarrow t_n \rightarrow t_0$

then there exists some $u_j$ in the cycle which is either held in INV mode by $t_j$ or needed in INV mode by $t_j$.

Proof: Let us assume that there is no such $u_j$. Then from Theorem 5-1 we know that at the time of deadlock

$\forall j \forall k (t_j \neq t_k \land t_k \neq t_j)$

This would mean that $u_j \notin \text{FV}(t_j \), \text{PV}(t_j)$ and that $FV(t_j)$ is a predecessor of $u_j$ and $u_{j-1}$ is equal to one of the latter two vertices if that vertex is a predecessor of the other vertex (note that since we have a deadlock cycle all $u_j$ will be distinct). With this information in hand, we can follow the steps given in the proof of Theorem 4-1 (basis step and Case 1 of the induction step) to show that such a cycle is not possible. Hence a contradiction and the theorem is proven.

Next we state the simple condition which guarantees freedom from cascading rollbacks.

Definition 5-2: We say a transaction satisfies The INV Lock Release (ILR) Condition if it releases all INV mode locks immediately after the acquisition of its first X mode lock (before any reading/modification of the item locked in X mode takes place and before any other locks are acquired).

Theorem 5-4: If all update transactions obey the ILR condition, in addition to the rules of SMP, then when a deadlock occurs there will exist at least one transaction which can be rolled back to break the deadlock without causing any cascading effect (i.e., without other transactions being forced to be rolled back as a consequence) and without having to restore the value of any data base item.

Proof: Let there be a deadlock cycle. Then choose some $u_j$ meeting the conditions of Theorem 5-3.

Case 1: $u_j$ is needed in INV mode by $t_j$.

From the rules of SMP we know that $t_j$ could have acquired only INV mode locks so far, and thus no updates can have been performed. Therefore $u_j$ can be rolled back by merely unlocking the INV mode locks it holds.

Case 2: $u_j$ is held in INV mode by $t_{j+1}$.

If $t_{j+1}$ is requesting an INV mode lock on $u_j$ then we have an instance of Case 1. Otherwise, note that due to the ILR condition $t_{j+1}$ could only be requesting an X mode lock on $u_j$ and that it must be its first X mode lock request. Since so far $t_{j+1}$ would have acquired only INV mode locks, it can be rolled back by releasing those locks.

The interesting thing to notice is that cascading rollbacks are avoided even if we choose to rollback an INV transaction completely (as opposed to partially). This is in contrast to what happens in the case of the pitfall protocol, where only a partial rollback of one of the transactions in the deadlock cycle will avoid a cascading rollback (see [9]).

Injudicious use of rollbacks can, while removing deadlocks, result in a set of transactions becoming involved in a situation in which each transaction in the set in turn causes another transaction in the set to be rolled back. Such a state of affairs has the potential to continue to occur indefinitely in the absence of outside interference, resulting in a dynamic analogue of deadlock which we call potentially infinite mutual preemption. In particular, if every deadlock is resolved only by
rolling back the INV transactions, which is what prevents cascading rollbacks, then it is possible for such a phenomenon to occur, but once such a transaction manages to get its first X mode lock then it is guaranteed to finish (assuming that the scheduling algorithm is fair in granting pending lock requests), although it might become involved in deadlocks after that point in time. Due to the way deadlocks are resolved here, the transaction will not be rolled back as a consequence of the latter deadlocks.

6. CONCLUSION

In this paper, we have given an example of how concurrency can be increased in data base locking protocols by separating the effects of the commutativity and the compatibility of multiple concurrent accesses of data items. In particular, we have introduced a new locking mode, INV, which is used solely for concurrency control and which does not grant any access privileges (read/write) to the holder of the lock on the associated data item. Thus the "operations" performed by a transaction on an item which is locked in INV mode are commutative with respect to any other transactions' operations on that item, even though the S and INV modes are incompatible. As a result, acquisition of an INV mode lock by a transaction on an item does not imply that the transaction be ordered in an equivalent serial schedule with respect to other concurrently active transactions which have locked (in whatever mode at whatever time) the same item.

We have presented a protocol that supports the INV mode of locking. We have examined the effects of this locking mode on the occurrence of deadlocks and have given some effective mechanisms for handling them. These results indicate that in some cases it is useful not to equate the commutativity and compatibility of locking modes as has always been done in previous models of concurrency control.

7. REFERENCES


